

ESEN

VISION BASED NAVIGATION IN GPS DENIED ENVIRONMENTS (EVNAV)

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VISION BASED NAVIGATION IN GPS DENIED ENVIRONMENTS

(EVNAV)

- Vision Based Navigation (1 Hz navigation data output)
- Image matching between gathered imagery and previously uploaded geo-registered aerial or satellite images
- Accurate enough to complete mission when GPS is unavailable
- Passive system (no transmission, can not be jammed or interfered with)

- No external system required for operation (relies on internal image database and built-in camera)
- Light, small, low power consumption
- Can be customized to warn against GPS Spoofing attacks
- Adaptable to a variety of platforms
- 2D position accuracy < 30 m 3D position accuracy < 50 m





